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Use of a quantitative pedicle screw accuracy system to assess new technology: Initial studies on O-arm navigation and its effect on the learning curve of percutaneous pedicle screw insertion

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Abstract

Background: A quantitative screw accuracy system is proposed that allows for high-fidelity discrimination between various methods of pedicle screw insertion. Our purpose was to study the utility of a quantitative screw accuracy scoring system to assess new imaging technologies and their effects on the minimally invasive spine learning curve.

Methods: By use of a hypothetical “perfect screw,” a scoring system is proposed that may be used to compare the position of a small number of screws inserted according to a desired optimal position. This study incorporates a retrospective review of imaging studies for 10 patients who underwent percutaneous pedicle screw placement with either navigation-assisted O-arm imaging or navigation-assisted C-arm imaging. For the learning-curve portion of the study, 2 cadaveric adult torsos were used for instrumentation. Computed tomography imaging studies were used in both studies to assess screw position in the pedicle and vertebral body in relation to an optimal screw by use of a quantitative scoring system to rate accuracy.

Results: The quantitative scoring system allowed a statistically significant accuracy difference to be ascertained between 2 different technologies using fewer data points than previously published methods. When this screw scoring system is applied to minimally invasive percutaneous pedicle screw insertion, an optimal screw position can be achieved with greater accuracy through navigation-assisted technology (O-arm with computer-assisted navigation). When the O-arm with computer-assisted navigation was used by a novice surgeon learning the technique of percutaneous screw insertion, screws were inserted in a shorter period without loss of accuracy. In contrast, use of the traditional C-arm fluoroscopy leads to a loss of accuracy with faster insertion times. Increased accuracy can be seen clinically when compared with fluoroscopic navigation.

Conclusions: The use of a quantitative scoring system allows for rapid assessment of screw accuracy. As additional technologies and new teaching techniques for pedicle screw insertion are developed, this scoring system may be useful as an early assessment tool.

Keywords: Navigation; Image guidance; Minimally invasive surgery; Spinal instrumentation; Scoring system
potential to injure these nearby nerves. Furthermore, fixa-
tion strength of the biomechanical construct may be ad-
versely affected by malpositioned hardware. Given these
issues, the importance of a rapid and reproducible method of
evaluating pedicle screw accuracy becomes paramount.

Previous methods to assess pedicle screw accuracy have
been inconsistent and relatively insensitive. In most series
hundreds if not thousands of screws were required to reach
statistically significant conclusions. Therefore we have
developed a graded numeric scoring system that compares
the 3-dimensional (3D) position of a given pedicle screw
relative to an ideal, “perfect” screw. In this study we deter-
mined whether our novel scoring system is a practical
method to rapidly assess new technology through its appli-
cation in the evaluation of 2 aspects of minimally invasive
surgery: the accuracy of minimally invasive pedicle screw
insertion using a new imaging technology, O-arm with
computer-assisted navigation (O-NAV), and the effect of
this new imaging technology on the MIS learning curve.

Methods

Evaluation of accuracy using a quantitative screw
accuracy scoring system

The accuracy of percutaneously inserted pedicle screws
was assessed postoperatively by use of high-resolution spi-
ral computed tomography imaging with 1-mm cuts. Screw
placement was scored on 6 graded parameters: screw
length; axial and sagittal trajectory; and medial, superior,
inferior, and lateral breaches (Fig. 1). Ten possible points
were given for each pedicle screw. A score of 10 was given
for an ideal screw that had the following characteristics: (1)
screw length equivalent to three-fourths the length of the
vertebral body; (2) screw trajectory within 5° of the axis of
the pedicle; (3) placement parallel to the superior endplate
in the sagittal plane; (4) absence of inferior and/or superior
breaches; (5) absence of medial breaches; and (6) absence
of cortical breaches. Each screw was then scored with re-
spect to these parameters as detailed in Fig. 2.

O-NAV technique

A navigation reference pin—a 5-mm fluted pin (Naviga-
tion Perc Pin; Medtronic Navigation, Louisville, Colora-
do)—was placed into the posterior superior iliac spine
(PSIS). Images of the spine were obtained by the O-arm and
stored in the navigation system computer. These acquired
images were related to the patient reference pin and navi-
gated instruments in 3D space by the navigation computer.
The O-arm was removed from the operative field once the
desired images were obtained. Up to 4 navigated images
could be seen at once on the O-NAV screen during pedicle
screw insertion (Fig. 2). The navigation pointer was used to
plan the incision. A 1.5-cm skin incision was made, and the
dorsal fascia was incised. The pedicle was entered by use of
a navigated Jamshidi needle (Medtronic Navigation, Louis-
ville, Colorado) ensuring proper 3D direction of the pedicle

![Fig. 1. Parameters of screw accuracy scoring system. Axial computed tomography scan showing parameters of length, medial and lateral containment, and trajectory (A). Sagittal computed tomography scan showing sagittal containment and sagittal trajectory parameters (B). The clinically relevant parameters (medial and lateral containment, axial trajectory) are weighted for greater impact on the scoring scheme.](http://ijssurgery.com/)

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screw. The needle was exchanged for a Kirschner guide-wire. The pedicle was then tapped by use of a hand drill to allow a port for screw entry. Finally, an appropriately sized pedicle screw was inserted with a navigated screwdriver.

**Technique for C-arm imaging with computer-assisted navigation**

Pedicle screws were placed by the technique described previously except that C-arm imaging with computer-assisted navigation was used instead of O-arm imaging. A detailed description of this technique was previously described.8

**Clinical accuracy evaluation**

The accuracy of percutaneous pedicle screws inserted by O-NAV was compared with the accuracy of screws placed with the C-arm with computer-assisted navigation (C-NAV). A single surgeon (C.W.K.) inserted 22 percutaneous pedicle screws in 4 patients using O-NAV. By use of O-NAV, 8 screws were placed at L5, 8 at L4, and 6 at L3. In the next series of 6 consecutive patients, 24 pedicle screws inserted by C-NAV were graded for comparison to the O-NAV group. Of the screws inserted by C-NAV, 9 were placed at L5, 9 at L4, and 6 at L3. Screws in S1 were not assessed. Accuracy was assessed postoperatively as described previously. C-NAV screws were matched by insertion level to O-NAV screws to reduce confounding variables. All C-NAV and O-NAV screws were inserted by the same surgeon (C.W.K.), who has several years of experience performing C-NAV procedures but limited experience in percutaneous pedicle screw insertion using O-NAV.

**Cadaveric learning-curve study**

To assess the learning curve of percutaneous pedicle screw insertion, a separate cadaveric study was performed. Adult cadavers were thawed and appropriately positioned on a radiolucent table. Pedicle screws were inserted with either C-arm fluoroscopy (C-NAV group) or the navigation-assisted O-arm technique as described previously (O-NAV). A single novice spine surgery fellow (G.J.R.) performed 32 percutaneous pedicle screw insertions on 2 cadavers from T10 to L5. A randomized insertion scheme, where screws were inserted in a nonlinear progression of vertebral levels, was generated a priori to control for bias. To further control for anatomic variance, the surgeon inserted screws in a “zigzag” pattern so that each sequential screw was placed in the contralateral pedicle. All O-NAV screws were sequentially placed according to this predetermined algorithm. After taking a short break, the surgeon then proceeded to insert all C-NAV screws following the same progression. The spine fellow had no previous experience inserting percutaneous pedicle screws with O-NAV and limited experience inserting screws with C-NAV. A total of 16 pedicle screws were inserted by C-arm fluoroscopy, and 16 pedicle screws were inserted by O-NAV. The learning curve was evaluated based on total time required to insert each pedicle.
screw and accuracy of screw placement as a function of chronologic screw insertion number.

Statistical analysis

Data collected for comparison of accuracy between O-NAV and C-NAV were statistically analyzed by use of a 1-way analysis of variance and Fisher’s comparison t test with $\alpha = .05$.

Results

Use of scoring system in clinical practice

Percutaneous pedicle screws inserted by O-NAV were found to have a significantly higher mean accuracy score than those inserted by C-NAV ($P = .0001$) (Fig. 3). The mean pedicle screw accuracy score by O-NAV was 9.00 ± 1.51. Pedicle screws inserted by C-NAV resulted in a mean accuracy score of 6.13 ± 1.85. In the O-NAV group, 50% of implanted screws received a grade of 10 of 10, whereas only 4% of screws in the C-NAV group received a grade of 10 of 10 ($P = .0005$). This level of statistical significance was ascertained by assessment of only 46 total pedicle screws.

Cadaveric learning-curve study

A cadaveric model was used to assess the learning curve of percutaneous pedicle screw insertion. A novice spine surgeon was assessed for screw insertion times and screw placement accuracy using either the traditional C-NAV technique or O-NAV technique.

Insertion times decreased with chronologic screw number. After the eighth screw, the total procedure time stabilized at a value of approximately 6 minutes (Fig. 4). However, screw accuracy decreased with further insertion when the C-arm was used. No loss of screw accuracy was observed when the O-arm was used. The mean accuracies of the initial 5 screws inserted and the final 5 screws inserted were compared for each technique by use of our graded, quantitative scale. With the C-arm, screws 1 through 5 had a mean accuracy score of 7.6 and a mean insertion time of 10.25 minutes whereas screws 12 through 16 had a mean accuracy score of 6.6 and a mean insertion time of 4.67 minutes. With O-NAV, screws 1 through 5 had a mean accuracy score of 8.2 and a mean insertion time of 11.06 minutes whereas screws 12 through 16 had a mean accuracy of 8.2 and a mean insertion time of 4.73 minutes. The higher accuracy score for the final 5 graded screws inserted by O-NAV as compared with the final 5 screws for C-arm was statistically significant ($P = .05$) (Fig. 5). These data show that the accuracy score is adversely affected as pedicle screws are inserted more rapidly by use of C-arm imaging whereas placement accuracy is not affected by more rapid insertion of screws by O-NAV.

Discussion

Although several grading systems for pedicle screw accuracy exist, they lack sufficient sensitivity to allow rapid assessment of new technologies. The importance of this issue is illustrated in the relatively slow adoption of MIS pedicle screw insertion. In the current state of MIS surgery, the key obstacle to adoption remains the difficult learning curve. In most studies several hundred screws to thousands of screws were examined to obtain a statistically
meaningful assessment of screw placement accuracy. Previous studies have compared the accuracy of pedicle screw placement between 2 technical modalities, both with open procedures and with minimally invasive procedures, through application of various scoring systems to postoperative computed tomography images. These studies evaluate accuracy by recording the presence or absence of a cortical breach or through grading in terms of breach severity. Assessment of so few parameters of relative infrequency results in an insensitive method of evaluation. As a result, large sample sizes have been required to discern the difference in screw accuracy between techniques. A recent study by Parker et al evaluated the accuracy of insertion of 6,816 pedicle screws by a freehand technique. They used a scoring system whose single parameter was absence or presence of a cortical breach. Another study, conducted by Devito et al, attempted to increase the sensitivity of accuracy assessment through discrimination of breach severity based on increasing 2-mm increments of screw protrusion outside the pedicle. This study used 3,271 pedicle screws for evaluation.

There is a need to assess accuracy more quickly in the clinical setting so that an undue number of patients are not exposed to unnecessary risk. Therefore we have developed a numeric, graded scoring system that compares the 3D position of a given pedicle screw relative to an ideal, “perfect” screw.

This quantitative accuracy scoring system allows for rapid discrimination of techniques using a small number of data points when used to assess pedicle screw accuracy and physician learning curve by use of O-NAV technology. We recognized a statistically significant difference in screw accuracy and a noticeable trend in learning curves with much smaller sample sizes as compared with previous methods of evaluation. In the clinical setting, navigation-assisted O-arm imaging (O-NAV) results in more accurate percutaneous pedicle screw placement than navigation-assisted C-arm imaging (C-NAV). Only 46 screws were necessary to show that O-NAV yielded higher overall accuracy scores than C-NAV, as well as significantly higher scores in clinically relevant subcategories of accuracy scoring.

On the basis of these observations, we sought to determine whether the O-NAV technology could decrease the learning curve associated with percutaneous pedicle screw insertion. Using a cadaveric model, a novice spine surgeon was tested on percutaneous pedicle screw insertion using standard C-arm imaging or O-NAV. Both imaging technologies produced a trend toward faster screw insertion times as a function of screw number. However, the screw accuracy score suffered with faster insertion times when the C-arm was used. In contrast, screw accuracy did not suffer with faster insertion times when the O-NAV technique was used. These results were obtained from analysis of only 32 total pedicle screws with the proposed scoring system.

The incorporation of multiple parameters, such as screw position in 3D space, in addition to cortical breaches, makes our proposed scoring system a more sensitive tool in accuracy evaluation than currently available methods. Furthermore, this scoring system is able to evaluate clinically important subcategories of screw position, such as medial and superior breaches, in addition to overall accuracy in 3D space. More weight was placed on medial and sagittal containment within the pedicle in an attempt to correlate a higher accuracy score to a more favorable clinical outcome. This clinical study was completed to showcase the ability of a novel quantitative scoring system to be a simple, consistent method to discriminate accuracy using a small sample size.

Conclusions

A quantitative screw accuracy scoring is described based on the concept of the ideal pedicle screw. By use of a numeric scoring system ranging from 1 to 10, screw insertion techniques can be compared with high fidelity, decreasing the number of screws requiring testing. This minimizes undue risk to patients when applying new technologies for MIS pedicle screw insertion. This may be particularly useful to assess the learning curve of minimally invasive percutaneous pedicle screw insertion via advanced intraoperative imaging technology.

References


